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9. A method according to claim 7 wherein the number of the sensors provided for corresponds to the number of pockets in a package.
10. A method according to claim 1 or 2 wherein the sensor is an optical three-dimensional image detection sensor.
11. A method according to claim 10 further comprising the step of detecting each pocket of the package by means of said sensor.
12. A method according to claim 11 wherein the number of the sensors provided for corresponds to the number of pockets in a row of the package.
13. A method according to one claim 11 wherein the number of the sensors provided for corresponds to the number of pockets in a package.

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